

care is required in the

design of the algorithms. Realistically, that kernel of

processing routines also

requires a simple operator

interface and the presenta-

tion of results must be both

interpreted. Marine operations personnel, in particular, must be able to make their decisions in real-time.

has

MWAVES directional wave

spectra software to addess

and

easilv

developed

quantitative

Nobska

these needs.

## **Fundamentals of Water Velocity Measurement**

## Directional Wave and Tide Measurements using the MAVS-5WTG and MWAVES Software

#### Introduction

Directing marine operations in harbors and coastal waters requires real-time knowledge of the directional wave spectrum and other statistical characteristics of the wave and current velocity field. Real-time and historical wave and tide statistics are also important for coastal engineering projects and for the investigation of coastal processes such as the erosion and deposition of sediments. Williams (NOBSKA) and Terray (WHOI) have shown that these properties can be calculated from integrated MAVS time-series measurements of velocity and pressure. However, the calculation is non-trivial, both numerically and for practical reasons, and



MAVS-5WTG Directional Wave and Tide Gauge

### **Specifications:**

Parameter	Accuracy	Resolution	Range
Speed	0.3cm/sec	0.03 cm/sec	200
Direction	+/- 2 deg	0.1 deg	360
Temperature	0.1 deg	0.03 deg	-5 to 45
Pressure	0.1% FS	0.024% FS	User-defined
	0.04% FS	0.024% FS	User-defined
Tilt	2 deg	0.1 deg	20

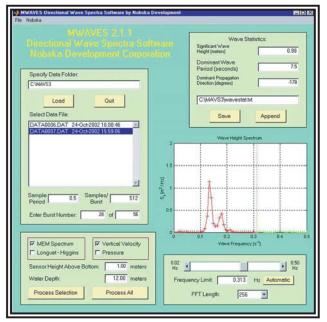
Optional Logging Memory: 1 GigaByte Maximum Direct Reading: RS-232 or RS-485

Power: 10-15 Volts DC

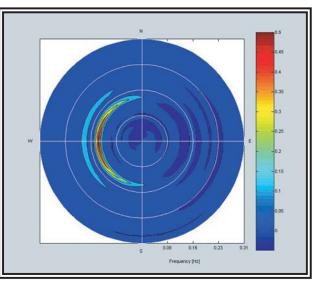
Optional sensors available upon request

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MWAVES Control Panel and Wave Height Spectrum



Polar Presentation of Directional Wave Spectrum

Data for plots courtesy of NWRI/CCIW Canada in Lake Ontario, 2002

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#### HTTP://www.NOBSKA.net

# **SPECIFICATIONS:**

Parameter	Accuracy	<b>Resolution</b>	Range
Speed	0.3 cm/sec	0.03 cm/sec	200 cm/sec (optional ranges available)
Direction	+/- 2 deg	1 deg	360 deg
Temperature	0.1 deg C	0.03 deg C	-5 to 45 deg C
Conductivity	0.2 mS/cm	0.02 mS/cm	0 to 75 mS/cm
Pressure	0.5% F.S.	0.024% F.S.	15, 30, 60, 450, 3,000, 7,500 & 10,000 PSI
	0.04% optional		
	0.08% optional		
Tilt	2 deg	0.1 deg	20 deg, 45 degree optional

#### Drift: NONE

Measurement Technique: Differential travel time, 3 axis

Acoustic Paths: 4 measured, 4 used

Power:

Internal Recording: 13.5 VDC, 18 AA Alkaline batteries, @ 4.8 Ah, optional lithium thionyl chloride 14.4 VDC @ 8.8 Ah Direct Reading: External 12-15 VDC Current Drain: 23 ma. Measuring 0.6 ma. Sleep Mode

Internal Recording Memory: 1 Gbyte compact Flash Card

Memory Usage: Dependent on sampling method and size of memory inst alled

Communications: TTL, RS-232 or RS-485 @ 38,400 baud maximum 115.2 K baud

Depth: 2,000 m. or 6,000 m.

- Dimensions: Standard 2,000 m MAVS Cylinder Diameter: 3.25 in. Overall Length: 25 in.
- Weight: Standard 2,000 m MAVS Water: 2.6 lbs.

Air: 5 lbs.

Mooring Frame: 2000 lbs. Optional 10,000 lbs. available

Sampling Rates: 10 Hz in Earth Coordinates (resolved to Ve, Vn, Vup) or 15 Hz in instrument coordinates 25 Hz Raw Data, No Compass, No Options

Sea Cable: RS-485 or RS-232 4 wire (inquire for other communication protocols)

- Data Record Size: Standard Instrument: 32 bytes per record for Day, Hour, Min, Sec, T, Tilt, Ve, Vn, Vu Recorded as Binary and transmitted as ASCII Comma separated variables with CR LF
- Operating Modes: Vector Averaging Burst Mode (programmed for timed sampling) Externally Triggered Sample Continuous Sampling
- Software: MAVSOFT Windows95, Windows98, Windows XP/NT user interface Terminal Emulator: Hyperterminal, Crosscut or Tattleterm Optional Graphical Software available upon request